Persian Gulf Soccer 2D Simulation
Team Description Paper 2017

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Abstract. In this paper, algorithms, methods and goals in Persian Gulf Soccer 2D Simulation team has been described. This article introduces approaches which we have utilized and implemented in Persian Gulf Soccer Simulation 2D team during its activity. Our defensive decision making and some useful software for debugging, training and holding matches have been discussed here. The base code that Persian Gulf has used is agent2d-3.1.1 and the library is librcsc-4.1.0 with little changes. Persian Gulf,Soccer 2D simulation, defensive decision making, intelligent formation detection, debugger, trainer, TPAS.

1 Introduction

Persian Gulf Robotic team has been formed by students of Shiraz University, Student Cooperation Office(SCO) and Islamic Azad University of Bushehr(IAUB). This team is a combination of some members of the best Iranian team (Shiraz) in World Cup 2016 competitions, some students of Artificial Intelligence, Software Engineering and Information Technology fields in Shiraz University and IAUB and also some talented members of SCO. Shiraz Soccer 2D Simulation team is the core of Persian Gulf Soccer 2D Simulation team and its members could achieve 1st place in IranOpen 2016 technical challenge, 5th place in IranOpen 2016 league and 6th place in RoboCup WorldCup Competitions 2016. The technical leader of the team was a active member of Cyrus 2D too and participated in many competitions since spring 2012. He achieved 1st place in IranOpen 2014, 5th place in WorldCup Brazil 2014, 8th place in WorldCup Netherlands 2013,
9th place in WorldCup China 2015 and 1st place in Kordestan 2013. He was also a member of soccer2D league technical committee of Kazeroon Robotic Competitions 2015. Moreover, Two of the members of this team participated in the soccer2D competitions like Iran Open 2015 and Kazeroon Robotic Competitions 2015. One of them could also participate in WorldCup China 2015 competitions and achieved 11th place between accepted teams as the leader of Genius 2D 2015 soccer2D team. Introducing novel approaches in soccer simulation, increasing accuracy of agents, reducing search space for agents’ decisions and using more artificial intelligent algorithms to make agents more dynamic are the most important goals of Persian Gulf team.

In the following, first our defensive decision making algorithm will be discussed; then, PersianGulf’s TPAS Software features and parameters will be demonstrated. Eventually, we will introduce our Trainer and DebugWatch software.

2 CDDMS Method

In traditional methods, each player makes his own decision for marking or blocking an opponent agent which would make team’s defense line so messy. In order to solve this problem, we utilize a central decision making algorithm that can fix the problem of such chaos.

We proposed a method which is called Central Defensive Decision Making (CDDMS). In CDDMS, we assign the job of decision making about our team’s defensive strategy to our goalie as our team leader in defense. Goalie has some specific features that help him to be the best leader in defense. For instance, he should always keep looking at the ball and also dangerous opponents; consequently, his information about ball and players is the most updated among others. By having the most updated information, goalie assigns each teammate, except our offender and himself, an opponent player. The most effective factors for this decision are our teammates’ current positions, opponents’ current positions and our teammates’ home positions which is their positions according to the current formation.

We divided the task of defense into two diverse sub-tasks. The first one is to find out the opponent player that each agent should cover. The second one is to choose between performing a block or a mark or none of them. In CDDMS, our goalie is responsible for the first sub-task in a way that he calculates the best teammate to cover dangerous opponents; then, by using say command, goalie tells players whom to cover and nothing more. After receiving the command, each player will understand his target opponent and based on ball position and opponent position he would select between marking or blocking actions. Figure 1 is an example of a message sent by our goalie to our teammates; this message contains a header and nine other cells which include the target opponent for our teammates with numbers 2 to 10 respectively. zero number in a cell means that there is no one to be marked or blocked for our teammate.

To mention the pros and cons of our algorithm, the most positive point here is an impressive reduction in defensive decision making chaos between teammates
and the most negative point here is that we have some limitations and occasional problems like unpredicted delays or collision of messages in the network that cannot be fixed now. Figure 2 represents how CDDMS works in our team and arrows in the picture represent assigned opponents to our teammates.

3 Software Development Project

In order to improve the quality and accuracy of actions in Persian Gulf, we needed some special software to facilitate the process of running, debugging and analyzing. To do so, we decided to implement three different software and we will discuss their features and capabilities in the following subsections.

3.1 Tournament Planning and Analyzing Software

Planning a tournament so that a number of teams play together based on a special order of facing each other is not always an easy task. More than that, current soccer server generates a logfile after each game that can be used to analyze the game. Handling the execution of the matches in a tournament and extracting the details of each team’s performance in defense, offense and midfield and many other interesting statistics can be performed by our proposed software.
Tournament Planning and Analyzing Software (TPAS) is a powerful tool written by Java language and is able to hold diverse types tournaments such as cup, league, world cup, a simple friendly match or even create arbitrary tournaments with arbitrary rules. Each tournament type has its own order of playing matches and corresponds to different real tournaments. For instance, in the cup mode, each team will quit the competitions if it looses against its rival; winning a match leads a team to the next round and it can be continued until the final match that a victory there makes the team the champion of the tournament. Figure 3 shows an overview of the software graphical interface and a sample cup with three teams and the table and result of the competition. Because soccer 2D simulation league in WorldCup competitions uses an specific method for holding matches in its different rounds in the recent years, we have put a world cup mode in our software to handle its tournament matches easily.

Fig. 3. A sample cup in Tournament Planning and Analyzing Software

TPAS lets us configure any tournament by just doing some clicks and in a well-designed graphical interface and keeps us away from server configurations complexities. Moreover, TPAS analyzes each game separately and generates some statistics about matches to help us learn more about our and opponents’ strengths and weaknesses.

3.2 Trainer

We changed some features in the soccer server and soccer monitor and developed a trainer that aids us to test and improve our algorithms in different controlled situations against other teams. It has a json configuration file that gets parameters including ball position, ball velocity, ball owner, movement margin for each team, game area margin, number of players for each team, period of each episode, condition of ending the episodes, number of total episodes, etc. for the training which we want to be simulated. Figure 4 shows a two-by-two training in which the left team is in the right side teams defensive area and wants to take the ball and get score but the right team wants to push the ball away from its defensive area to make the situation safe.
4 DebugWatch

Debugging an agent’s code is not easy during an implementation of a high-level algorithm. Most of the actions involve more than one cycle and need to be considered in a sequential timeline so that we find the time in which agent makes a wrong decision. Besides that, we need to check more than just one parameter and handling a lot of parameters and checking them in a row for different cycles requires special effort that is not constantly feasible. To make debugging process easier, we have designed a new software that helps you debug your problems during the match. It can be cooperate with soccer logplayer so as to synchronize the debugging process in both graphical and textual aspects. Figure 5 represents DebugWatch window. In this example, we have printed the x and y coordinates of each player. In traditional methods, we had to check each agents outputs separately in different files and it was a very time consuming task. By utilizing Debug Watch we are able to see all agents outputs in each cycle just in a moment.
5 Conclusion and Future Work

In this description paper we introduced Persian Gulf soccer 2D simulation defensive strategy and three efficient software that pave the way to amend our team performance much easier and faster. Having a central defensive decision making system is crucial for keeping your defense line’s discipline and arrangement and we tried to fill the gap of the base in this part at first.

We are working on a perfect analyzing tool that will be added to TPAS to extract the most possible information from every match. We need some information during the match such as our opponents’ formation in different situations; we use a formation detection system but it has some defects that we are working on it. Moreover, our pass accuracy and defensive actions need to be revised and some corrections are needed in agents’ movements.

References